System for testing multi imaging/laser systems

Questionnaire for potential buyers

The main application of MS test system is testing multi-imaging/laser system. If testing stand alone imagers (thermal imagers, VIS-NIR cameras, SWIR cameras or stand alone laser systems (LRF, pointers, designators) is the main application then please consider specialized test systems like DT, TVT, ST, LUNI, L64.

The questionnaire is divided into two part: 1)Basic questionnaire, 2)Detail questionnaire. The first part presents questions about basic features of tested multi imaging/laser system. The second part presents questions on details of design of multi-sensor systems. It is perfect if both parts are filled. However, even basic questionnaire gives valuable information about tested multi imaging/laser systems that enables to prepare optimal proposal.

Dear customer, please note that the higher number and ranges of the requirements marked in this questionnaire will have direct influence on the price of proposal version of MS test system.

1 Basic questionnaire

1. What is list of main types of multi imaging/laser systems to be tested?

Туре	Image of exemplary device
☐ gimbal type multi imaging/laser systems,	Chus Constant
□ pan-tilt type multi imaging/laser systems,	
□ box type multi imaging/laser systems,	
□ binocular/monocular portable multi imaging/laser system,	
other:,	

If it is possible please attach the images of systems similar to your system (internet data).

2. What types of imagers are used to built multi imaging systems to be tested:					
\Box_{LWIR}	\square MWIR	U VIS/VIS-NIR	\Box_{SWIR}	□ Other:	

3. What is aperture of biggest optical objective used by imagers in your system?

4. What are simulated illuminance conditions when testing VIS-NIR imagers/SWIR imagers \Box Day



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□ Night □ Day & Night

6. What is minimal diameter of a circle that overlaps totally optics of all sensors (imagers/lasers) of your multi-imaging/laser systems?

7. What is approximate minimal range to detect human target using your tested imagers?.....

8. What is approximate maximal range to detect human target using your tested imagers?

9. Do you want to check boresight of laser to imager? \Box Yes, \Box No

10. Do you want to test laser (measure performance parameters) \Box Yes, \Box No

Some customers what only to check boresight of laser to imagers. Measurement of performance parameters of lasers/LRFs – not needed.

11. Choose protection level of the test systems when high pulse energy lasers (pulse energy >10mJ) are tested:

□ Low level: optical attenuators manually located at	□ High level: test system capable to withstand high pulse
collimator output opposite laser	energy lasers even if user forgets to locate properly optical
	attenuators.

Low protection level is typically offered by typical test systems. If user forgot to use properly located optical attenuator then collimator flat mirror or laser meters can be damaged when testing high pulse energy lasers (especially 1064nm pulsed lasers). High protection is offered by Inframet test systems based on modified collimator and laser meters that protect system even if attenuators are not used. High protection level is not needed when only low power multi pulse LRFs are to be tested.

12. What are your budget preferences

Cheapest option Typical version comparable to offered on the world market	Advanced option
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2 Detail questionnaire

1. Please fill in the table with detail informations about imaging systems to be tested:

Spectral range	Maximum aperture	Nyquist frequency	Parameters to be measured		
□ _{LWIR}		Min.: Max.:	□ MRTD □ _{NETD} □ _{SiTF}	□ FOV □ Other:	
□ _{MWIR}		Min.: Max.:			
U VIS/VIS-NIR		Min.: Max.:	□ Resolution □ MRC (for performance of	□ _{FOV} □ _{Other:}	
□ _{SWIR}		Min.:	VIS-SWIR imager against low		



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	Max.:	contrast targets) SiTF NEI 	
Other:	 Min.: Max.:	□ Other:	

2. What is preferable spectrum of light source used to test VIS-NIR/SWIR imagers \Box Halogen Polychromatic 2856K, $0.4 - 2 \mu m$ or \Box LED Polychromatic >5000K, $0.4 - 0.9 \mu m$?

Halogen source offers wider spectral band. LED source offers more realistic day illuminance conditions and much longer life time.

- 3. What are types of boresight errors of your multi-imaging/laser systems are to be tested?
- \Box Imager to imager (example: misalignment between thermal imager and VIS-SWIR imager),
- \Box Imager to laser (misalignment between thermal imager and transmitter of laser range finder)
- \Box Imager to reference mechanical plane (valid for imagers having such reference mechanical plane).
- 4. Please fill in the table with informations about laser systems to be tested:

Туре	Туре	Wavelength	Pulse energy	Parameters to be measured
□ Pulsed	 ☐ Mono-pulse laser range finder (low PRF, high pulse energy) ☐ Multi-pulse laser range finder (high PRF, low pulse energy) ☐ Laser designator ☐ Other: 	$\begin{array}{ c c c }\hline & 1064 \text{ nm} \\\hline & 1540 \text{ nm} \\\hline & 1550 \text{ nm} \\\hline \end{array}$	□ <1mJ □ <10mJ □ <100mJ	Transmitter channel: Pulse energy Beam divergence angle Pulse peak power Pulse width PRF Other: Receiver channel: Distance simulation Distance accuracy Other:
Continuos	Laser pointer Other:	· ·	$ \square <1 W/mrad^{2} \square <10 W/mrad^{2} \square <100 W/mrad^{2} $	 Optical mean power Beam divergence angle Other:

5. Do you need optical table to be delivered by Inframet

 \square No \square Optical table for test system \square Optical table for test system and tested system:

Required space for tested system:

6. What are video interfaces used by tested imagers (mark up to four interfaces):

7. Please fill in the table with informations about other informations about systems to be tested:

□ Analog

- □ USB 2.0 (DirectShow)
- □ USB 3.0 (DirectShow, Gemicam)
- Camera Link



☐ HD-SDI/HDMI	
$\Box_{\rm LVDS}$	
$\exists_{\rm GigE}$	
□ GigE □ CoaXPress	
Custom:	

Special conditions

8. Will the tested system be used in vacuum chamber ? \Box Yes, \Box No

9.Will the tested system be used in cleanroom? \Box Yes, \Box No

10. Will the tested system be used in temperature chamber? \Box Yes, \Box No

Version 1.4

